

An optimum time-stepping Scheme for N-body Simulations

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Content

- General idea and description
- Implementation within tree-code
- Behaviour and tests

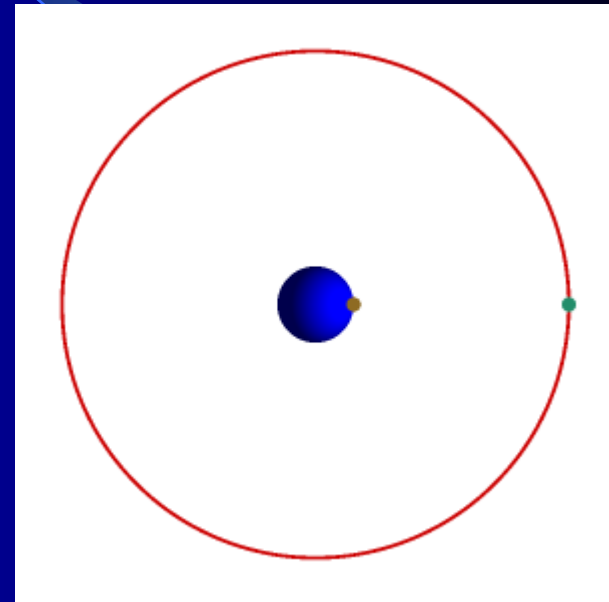
General Idea

- What is the natural time-scale?

Dynamical Time

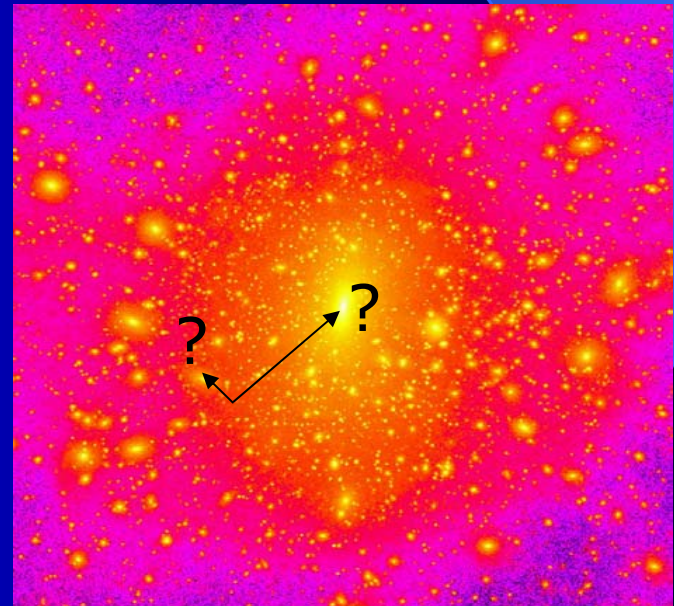
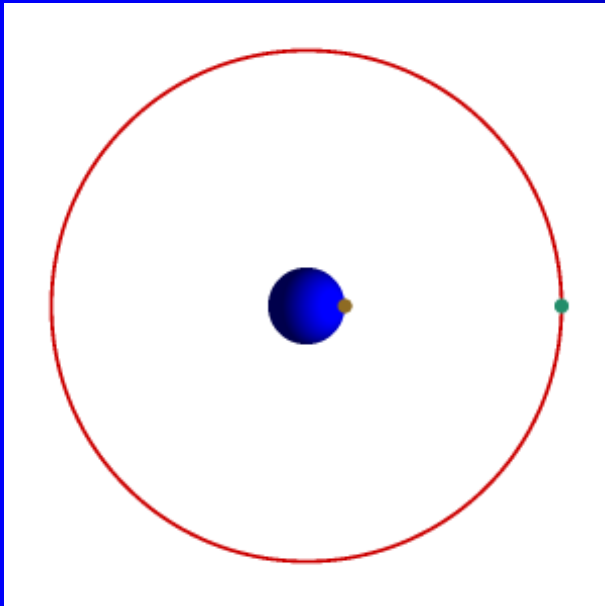
$$T_{\text{dyn}}(r) = \frac{2\pi}{\sqrt{G\rho_{\text{enc}}(r)}}$$

$$\rho_{\text{enc}}(r) \equiv M(r) / r^3$$



Dynamical Time-Stepping

- Natural choice $\Delta T \sim T_{\text{dyn}}$
- But what sets the dynamical time?



Two Regimes

- Mean field regime
 - global potential
 - no short range contributions
 - ⇒ ρ_{enc} set by global structures
- Gravitational scattering regime
 - large angle scattering
 - 2-body orbits with $e \rightarrow 1$
 - ⇒ ρ_{enc} set by local structures

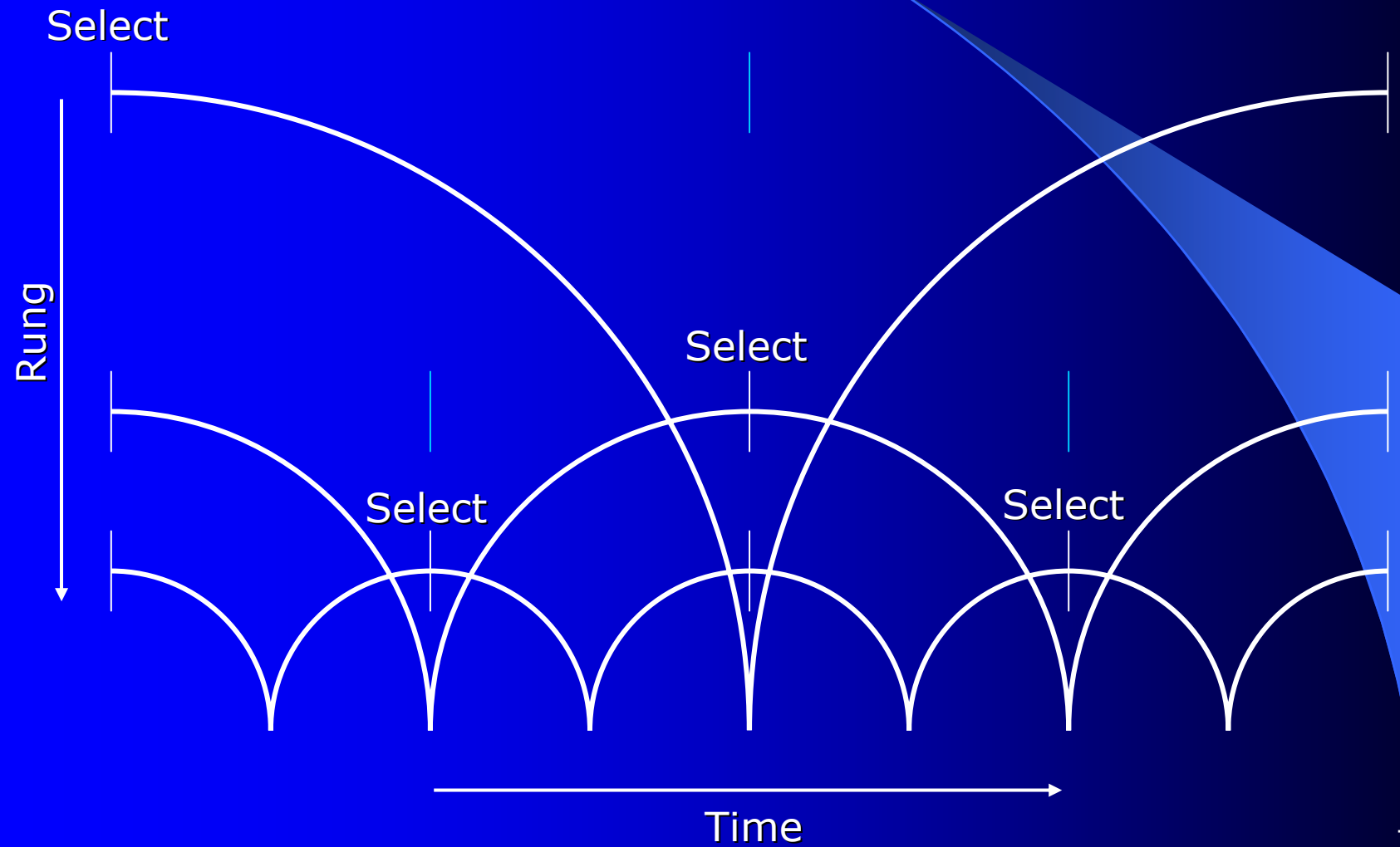
Implementation

- Block time-steps

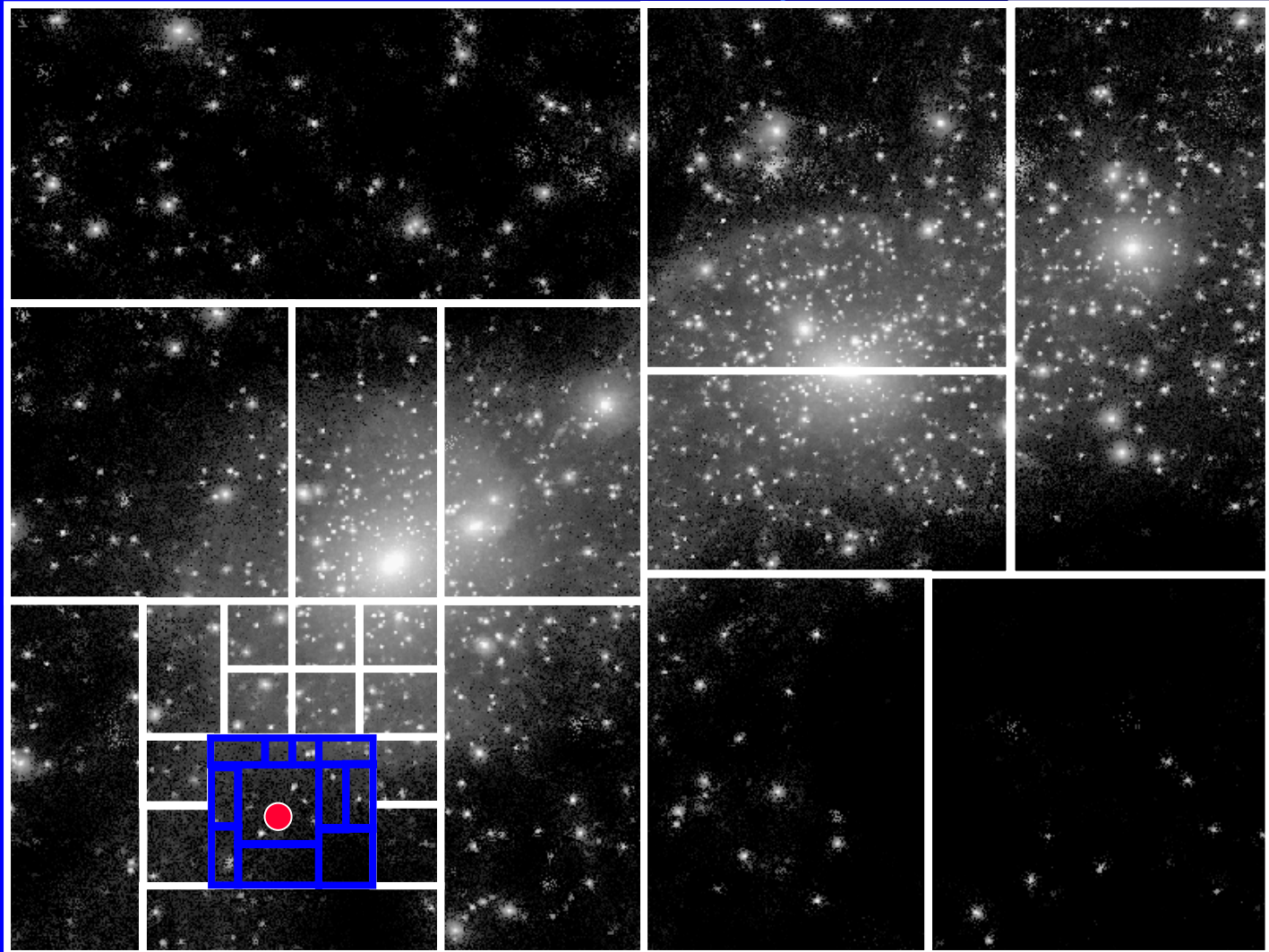
$$\Delta T = \frac{T_0}{2^n} \leq \eta_D \frac{1}{\sqrt{G\rho_{\text{enc}}(r)}}$$

- η_D is free parameter
⇒ controls number of time-steps per orbit

Kick-Drift-Kick Leapfrog



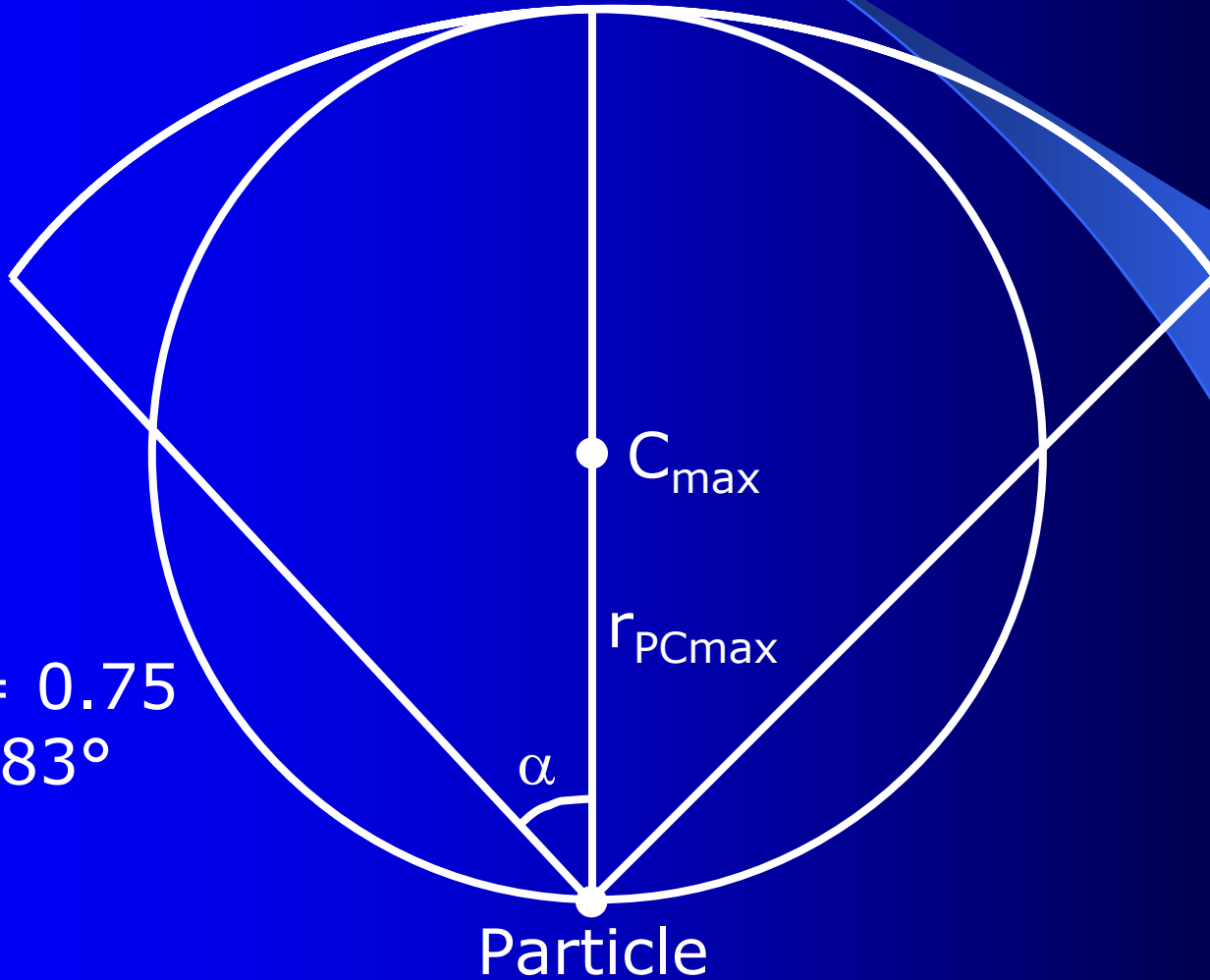
Mean Field



Mean Field Algorithm I

- Calculate $\rho_{\text{enc}} = M_C / r_{\text{PC}}^3$ for each cell
- Pick out the top 0.5 % values
- Sum up ρ_{enc} values within viewing cone
- Set maximum as $\rho_{\text{enc, MF}}$
- Add local density ρ_{local}

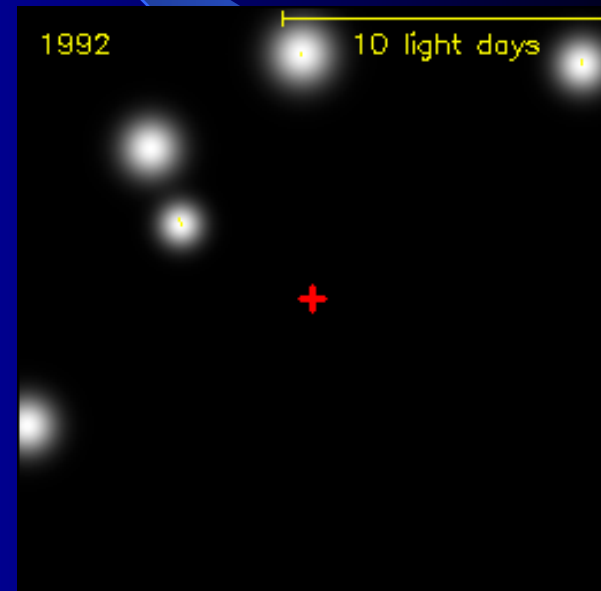
Mean Field Algorithm II



$$\cos(\alpha) = 0.75$$
$$\Rightarrow 2\alpha \approx 83^\circ$$

Gravitational Scattering

- We also want to follow 2-body orbits with $e \rightarrow 1$ correctly (elliptic & hyperbolic)
- gravitational scattering
- new time-stepping is starting point but...



Eccentricity Correction I

- PKDGRAV: Kick-Drift-Kick Leapfrog
- Approximate Hamiltonian

$$H_A = H_0 + \Delta T^2 H_2 + \Delta T^4 H_4 + O(\Delta T^6)$$

$$H_0 = H_D + H_K = H$$

$$H_2 = \frac{1}{12} \{ \{ H_K, H_D \}, H_D \} \\ - \frac{1}{24} \{ \{ H_D, H_K \}, H_K \}$$

Eccentricity Correction II

- Plug in Hamiltonian for 2-body problem and evaluate at periapsis of orbit with symmetrised time-step

$$\Rightarrow E_2^{\text{peri}} = \Delta T^2 H_2 = \frac{1}{24} \frac{(1+2e)}{(1-e)} \frac{\eta_D^2 GM_1 M_2}{a}$$

GS Algorithm

- Use symmetrised ρ_{enc} !

$$\rho_{\text{enc,GS}} = \frac{(1 + 2e) M_p + M_I}{(1 - e) r_{\text{PP}}^3}$$

- Similar to expression for orbital time in 2-body problem

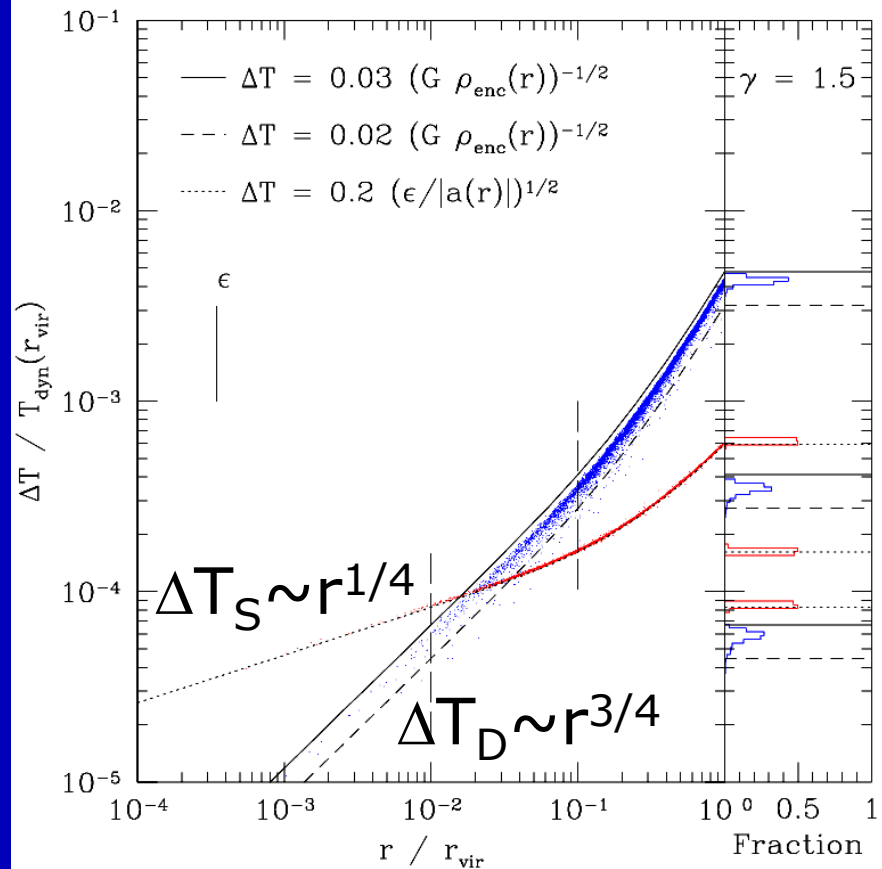
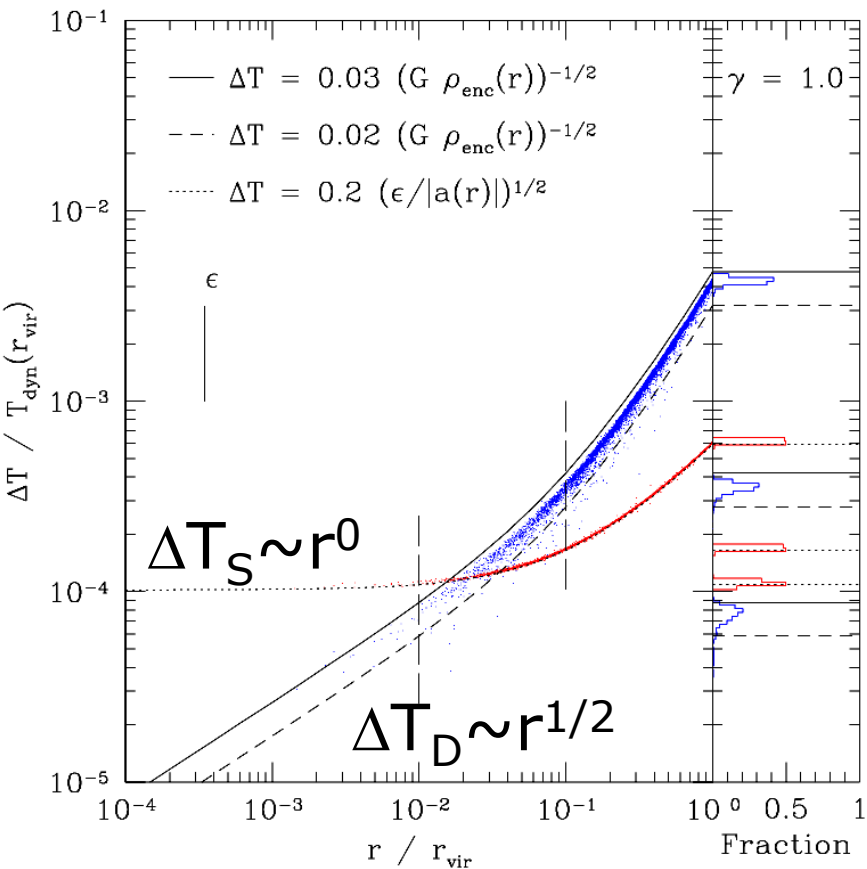
Standard Criterion

- Standard criterion used in PKDGRAV and GADGET

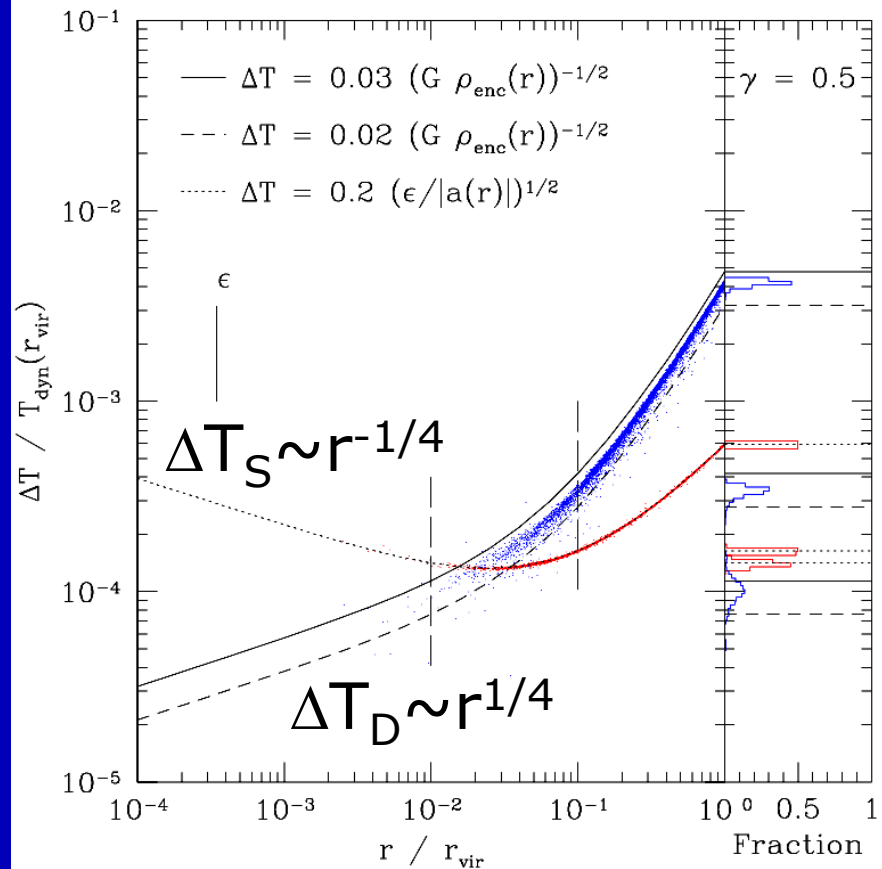
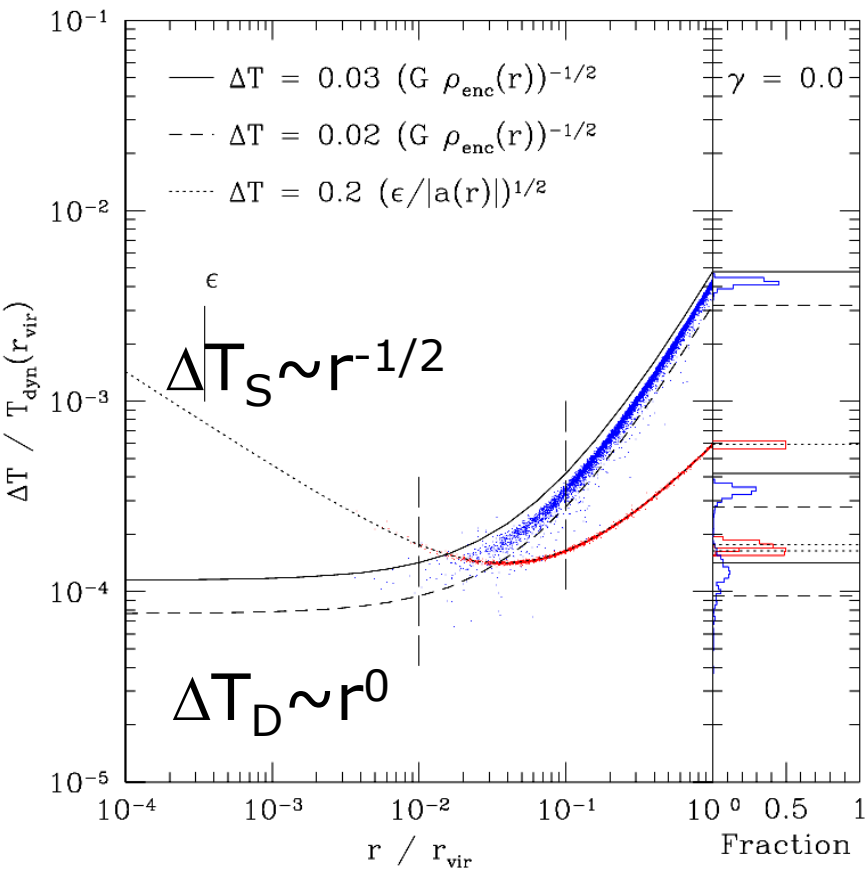
$$\Delta T = \frac{T_0}{2^n} \leq \eta_s \sqrt{\frac{\varepsilon}{a(r)}}$$

- Ad-hoc criterion
⇒ no physical motivation!
- Dependence on artificial simulation parameter softening length ε

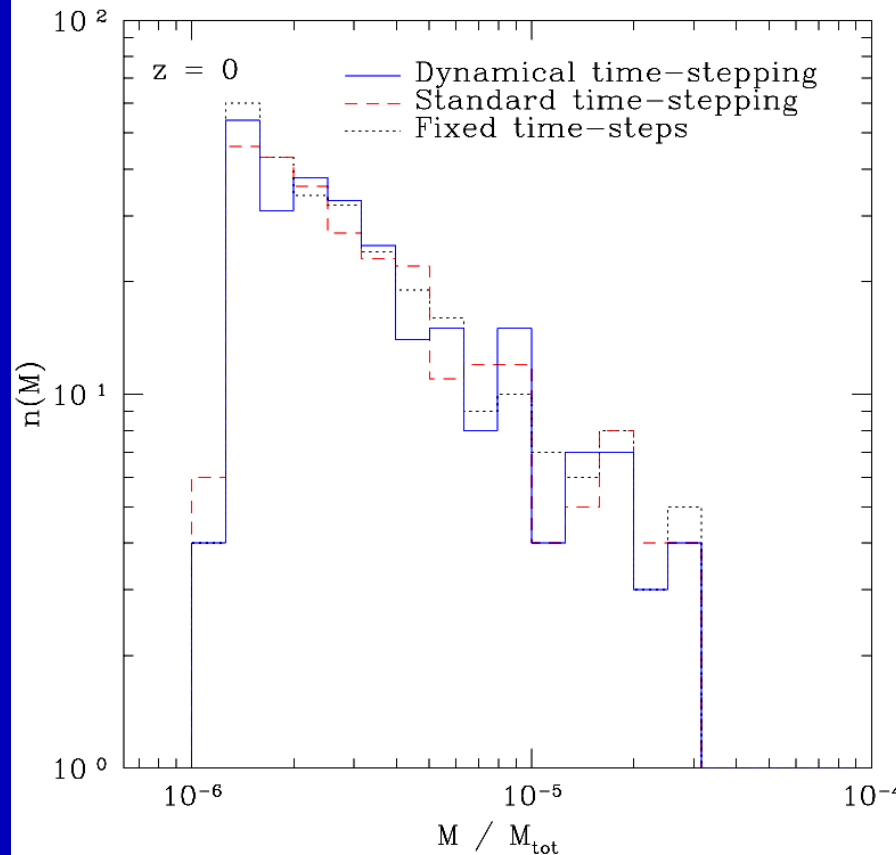
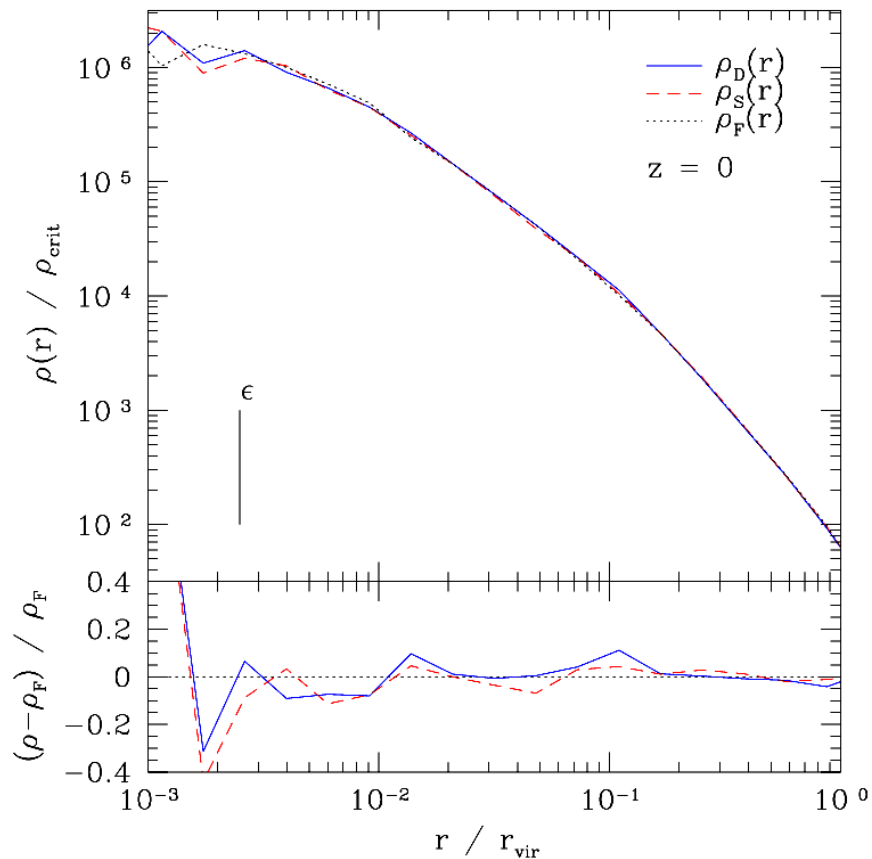
Comparison I



Comparison II

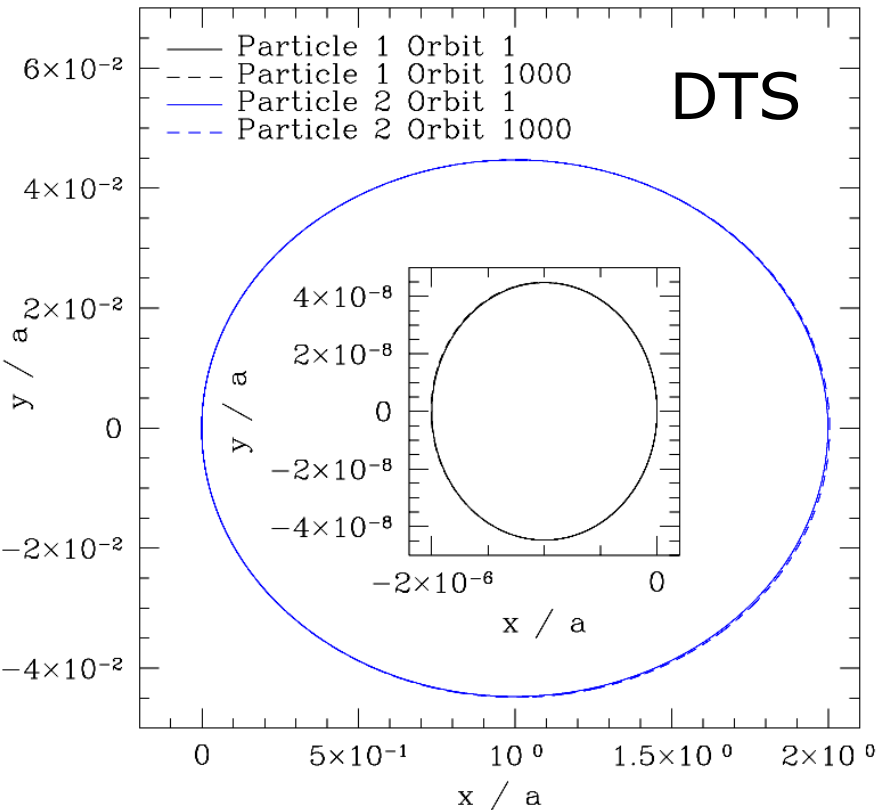


Cosmological Run



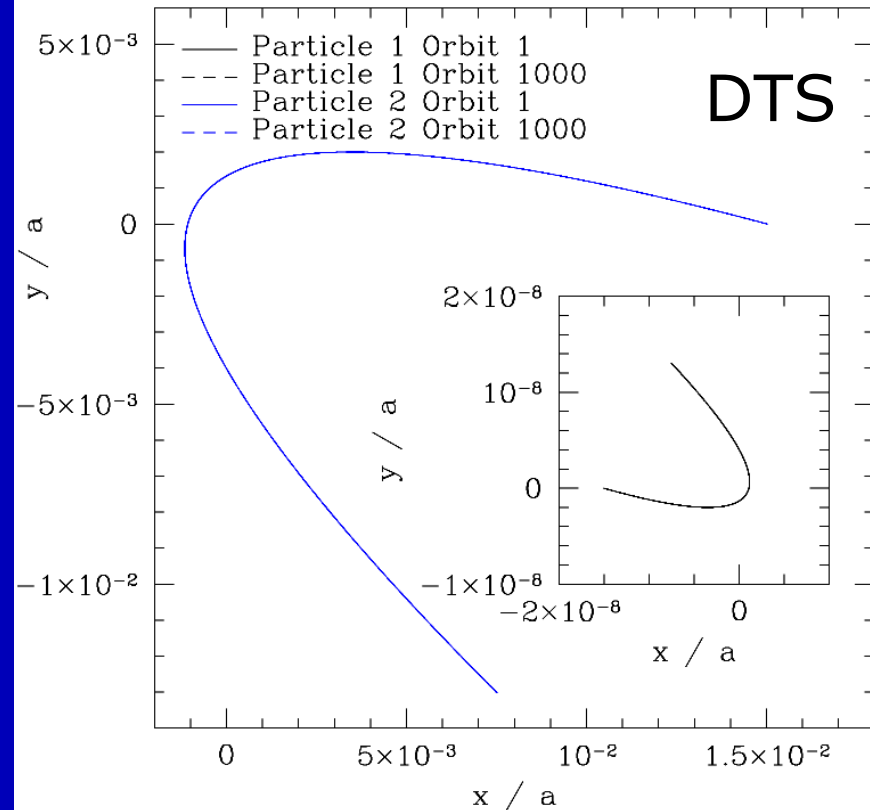
2-body Orbits I

Run 1) / $e = 0.999$ / $M_1/M_2 = 10^6$



$$\Delta E/|E_0| \approx +2.8 \times 10^{-3}$$

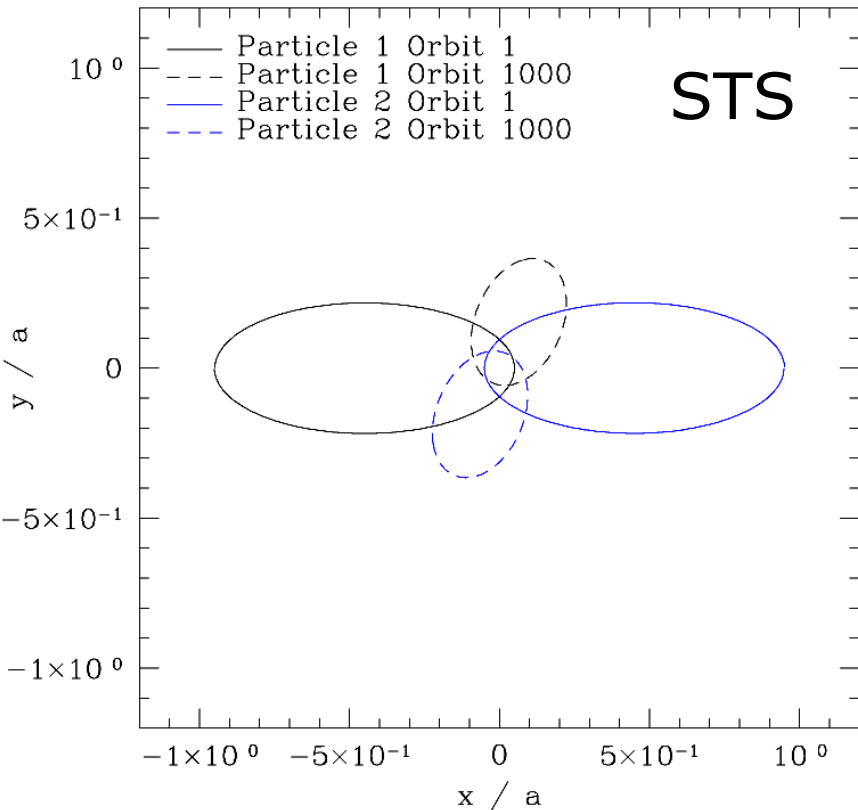
Run 1) / $e = 1.001$ / $M_1/M_2 = 10^6$



$$\Delta E/|E_0| \approx -1.3 \times 10^{-2}$$

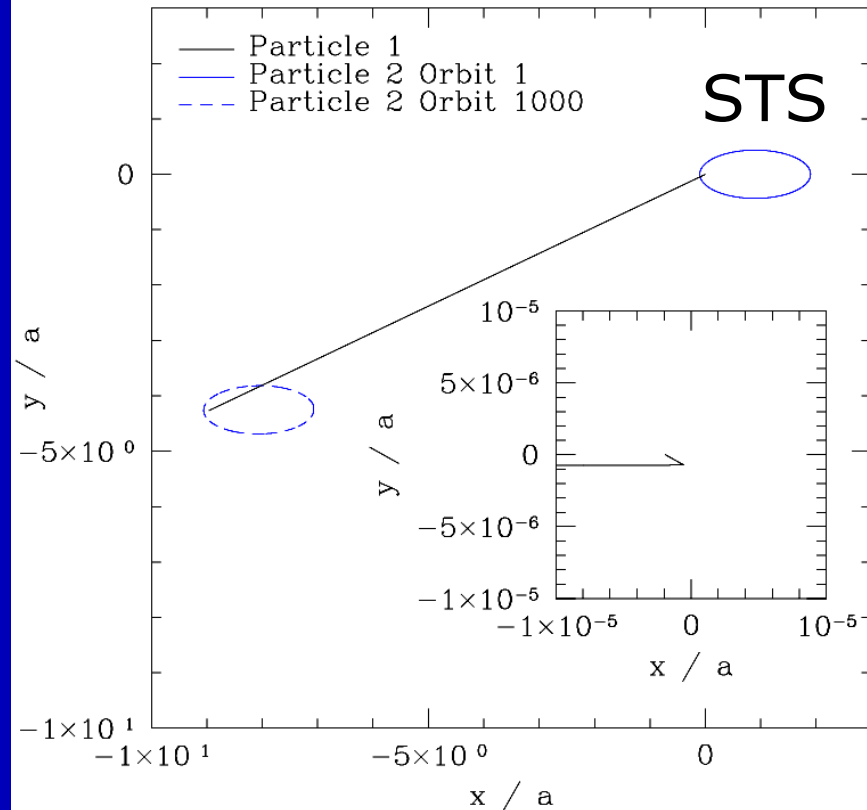
2-body Orbits II

Run n) / $e = 0.9$ / $M_1/M_2 = 10^0$



$$\Delta E/|E_0| \approx -1.3$$

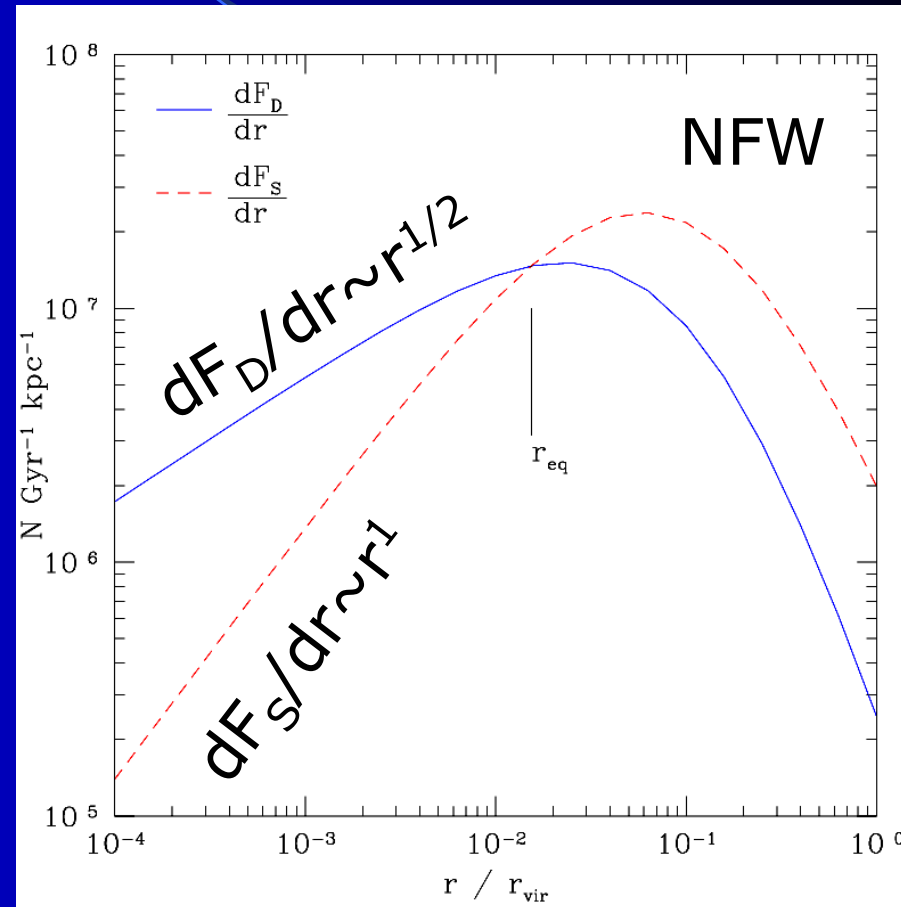
Run p) / $e = 0.9$ / $M_1/M_2 = 10^6$



$$\Delta E/|E_0| \approx +1.9$$

Efficiency

- Force evaluations per Gyr
- $F_D = \int dF_D dr \sim N$
- $F_S = \int dF_S dr \sim N^q$
- q depends on scaling of ε
- $\varepsilon \sim N^{-1/3}$
 $\Rightarrow q = 7/6$



Conclusions I

- DTS does not directly depend on artificial parameters like softening
- It gives physically correct time-steps in haloes with arbitrary central slope

Conclusions II

- It is faster in high resolution simulations
- Orbits with $e \rightarrow 1$ are followed correctly
- It allows to follow complex dynamical systems where scattering events are important